## AA 372

## Homework II

Please submit your codes together with your write-ups. Please email/meet me if something is unclear.

1. Lax-Wendroff Method: In class we showed that the forward in time centered in space (FTCS) scheme for advection equation,

$$
\begin{equation*}
\frac{\partial f}{\partial t}+u \frac{\partial f}{\partial x}=0 \tag{1}
\end{equation*}
$$

is unconditionally unstable. FTCS is first order accurate in time and second order accurate in space. We can construct a method which is second order accurate in both space and time as follows. Recall that the the second order accurate approximation in time for $\partial f / \partial t$, centered at $(i, n)$, is

$$
\frac{\partial f}{\partial t}=\frac{f_{i}^{n+1}-f_{i}^{n}}{\Delta t}-\frac{\Delta t}{2} \frac{\partial^{2} f}{\partial t^{2}}+\mathcal{O}\left(\Delta t^{2}\right)
$$

Using Eq. 1 we can express $\partial^{2} f / \partial t^{2}$ as $u^{2}\left(\partial^{2} f / \partial x^{2}\right)$. Thus, the second order accurate method (both in space and time) is

$$
\begin{equation*}
\frac{f_{i}^{n+1}-f_{i}^{n}}{\Delta t}-\left(\frac{u^{2} \Delta t}{2}\right) \frac{f_{i+1}^{n}-2 f_{i}^{n}+f_{i-1}^{n}}{\Delta x^{2}}+u \frac{f_{i+1}^{n}-f_{i-1}^{n}}{2 \Delta x}=0 \tag{2}
\end{equation*}
$$

where we have used the centered in space (and hence second order accurate) expressions for $\partial f / \partial x$ and $\partial^{2} f / \partial x^{2}$. Eq. 2 is known as the Lax-Wendroff scheme for advection equation.
Perform the von Neumann stability analysis (VNSA) on Eq. 2. What is the limit on $u \Delta t / \Delta x$ such that the amplification factor is $\leq 1$ ? This limit is known as the Courant-Friedrichs-Lewy condition and is generally applicable for all stable methods solving the advection equation (and to hyperbolic/wave equations in general where $u$ is replaced by the fastest signal speed).
Is Eq. 2 consistent with the advection equation (Eq. 1)? Will the solution converge to the correct result as $\Delta x, \Delta t \rightarrow 0$ ? Write the modified equation for the Lax-Wendroff scheme. Is the leading order error term dispersive or diffusive? How does it connect to VNSA?

We will come back to this once we start with PDEs.
2. Thomas Algorithm for tridiagonal systems: Write a program, in the language of your choice, to solve a tridiagonal system of equations $A x=d$, where $A$ is a tridiagonal matrix,

$$
A=\left[\begin{array}{ccccccc}
b_{1} & c_{1} & & & & & \\
a_{2} & b_{2} & c_{2} & & & & \\
& a_{3} & b_{3} & c_{3} & & & \\
& & & \ldots & & & \\
& & & a_{n-2} & b_{n-2} & c_{n-2} & \\
& & & & a_{n-1} & b_{n-1} & c_{n-1} \\
& & & & & a_{n} & b_{n}
\end{array}\right] .
$$

Use Thomas algorithm with forward elimination and back-substitution as discussed in class. As discussed in the class, a tridiagonal system is obtained when performing cubic spline interpolation.

Another situation where an almost-tridiagonal system results is when writing the implicit finite-difference formula (first order accurate in time and second ordered accurate in space) for the heat diffusion equation,

$$
\begin{equation*}
\frac{\partial f}{\partial t}=D \frac{\partial^{2} f}{\partial x^{2}}, \tag{3}
\end{equation*}
$$

given by

$$
\begin{align*}
& \quad \frac{f_{i}^{n+1}-f_{i}^{n}}{\Delta t}=D \frac{f_{i+1}^{n+1}-2 f_{i}^{n+1}+f_{i-1}^{n+1}}{\Delta x^{2}}, \text { or }  \tag{4}\\
& A f^{n+1}=f^{n} \tag{5}
\end{align*}
$$

where

$$
A=\left[\begin{array}{ccccccc}
b_{1} & c_{1} & & & \ldots & & a_{1} \\
a_{2} & b_{2} & c_{2} & & & & \\
& a_{3} & b_{3} & c_{3} & & & \\
& & & \ldots & & & \\
& & & a_{n-2} & b_{n-2} & c_{n-2} & \\
& & & & a_{n-1} & b_{n-1} & c_{n-1} \\
c_{n} & & & \ldots & & a_{n} & b_{n}
\end{array}\right] ;
$$

$f^{n+1}$ and $f^{n}$ are vectors at times $t^{n+1}$ and $t^{n}$ respectively; $b_{i}=1+$ $2 D \Delta t / \Delta x^{2}, a_{i}=-D \Delta t / \Delta x^{2}$, and $c_{i}=-D \Delta t / \Delta x^{2}$. Notice that we have used periodic boundary conditions; this results in appearance of
$a_{1}$ and $c_{n}$ in corners apart from the tridiagonal structure. Thomas method can be modified to solve Eq. 5 using the Sherman-Morrison formula. Sherman-Morrison formula states that the solution of the matrix equation

$$
\begin{equation*}
\left(A+u v^{T}\right) x=d, \tag{6}
\end{equation*}
$$

where $u$ and $v$ are column vectors ( $v^{T}$ is the transpose of $v$ ), is given by solving

$$
A y=d, A q=u
$$

and computing $x=y-q\left(v^{T} y\right) /\left(1+v^{T} q\right)$. To solve Eq. 4 you will need to choose column vectors $u$ and $v$ appropriately and apply the tridiagonal method twice. Hence the solution is $\mathcal{O}(n)$, where $n$ is the number of grid points.
Write a code to solve the diffusion equation (Eq. 3) using periodic boundary conditions with the method discussed above and the tridiagonal code that you wrote. Use $D=1$ and a domain going from 0 to 1 . The initial condition is $f=1$ for $0.4<x<0.6$; outside this $f$ vanishes. Find the solution $(f)$ at time $t=0.025$; choose the timestep $\Delta t=4 \Delta x^{2} / D$. Use 256 grid points such that $\Delta x=1 / 256$. See how the solution at $t=1$ converges with increasing resolution. Plot L1 Richardson error as a function of $\Delta x$ on $\log -\log$ scale; what is is order of convergence?
Bonus: Perform VNSA on Eq. 4 and show that the implicit method is unconditionally stable. Can you reach the same conclusion using the modified equation?

